

### "Your Direct Source for Condition Monitoring, Test & Measurement"

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## ROS - Remote Optical Sensor

CE

### SPECIFICATIONS:

3.3 - 15 Vdc @ 40mA Speed Range: 1-250,000 RPM Power Requirement: Illumination: Visible Red LED On-Target Indicator: Green LED on end cap Operating Temp.: -40° to 180° F [-40° to 80° C] Lens: Acrylic Plastic

Operating Range: up to 36" [0.9 m] and 45 degrees from target

ROS-P and ROS-W: 8 feet [2.4 m]; ROS-P25: 25 feet [7.6 m] Cable Length:

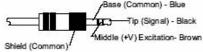
3.5 mm [1/8 inch] male stereo plug (ROS-P, ROS-P25); Tinned wires (ROS-W) Connection: 303 Stainless Steel supplied with two M16 Jam Nuts and Mounting Bracket Material: Dimensions: Threaded Tube 2.90 in x 0.62 in diameter [M16 x 1.5 x 74 mm] long

### CONNECTION DETAIL for Tinned Wires (ROS-W):

Wire Color

Function Positive Power Supply Brown (Com) Blue Black Common Signal (+V to 0 Vdc Pulse) (Sig) Housing Ground Shield

# CONNECTION DETAIL for Plug (ROS-P):







### OPERATING INSTRUCTIONS:

The ROS Remote Optical Sensor is capable of detecting a reflected pulse from a target consisting of Reflective Tape at In a ROS Remote Optical sensor is capable of detecting a reversed pulse from a target consisting of Reflective Tape at distances of up to 36 inches [1 m] from the rotating object and angles up to 45 degrees. For most applications, a ½" [12 mm] square piece of Reflective Tape (T-5) should be applied to a clean area on the rotating object. The Sensor should be mounted and optically aligned to illuminate the target once per revolution. The green LED On-Target indicator will blink at the input frequency rate when the ROS is properly almed. It is recommended that the optical Sensor be placed at a slight angle (15 degrees) from perpendicular, so that the Sensor will receive only pulses from the reflective marker. The ROS should be at least 1 inch from the reflective target to avoid false triggering. The Sensor is supplied with a set of two M16 is provided and a 90° engle elimination breaket. jam nuts and a 90° angle aluminum mounting bracket.

The ROS-P will work directly with all Monarch Handheld Tachometers and Nova-Strobe DA+/DB+ and PB Stroboscopes. A sensor power supply (SPS) with BNC output is available for those applications that require a separate power source for the sensor. The ROS-W will work with all Monarch panel instruments that accept pulse inputs (e.g. ACT Series).

The ROS is supplied with an 8 foot [2.4 m] cable terminated with 4 tinned wires (ROS-W) or a 3.5 mm [1/8 inch] male stereo plug (ROS-P) or optionally a 25 foot [7.6 m] cable terminated with a 3.5 mm [1/8 inch] male stereo plug (ROS-P25). The plug may be cut from the cable and the leads stripped and connected as shown in connection detail for tinned wire above. An optional 25 foot [7.6 mm] extension cable EC-25P is available with a female socket for the plug on one end, and a 3.5 mm [1/8 inch] male stereo plug on the other. Power requirement is 3.3 - 15 Vdc at 40 mA. The output pulse will be negative going at the applied voltage (+V).

The user must hold "steady" or mount the ROS to obtain an accurate measurement. The green LED on the ROS is the On-Target Indicator. NOTE: The green LED On-Target Indicator will blink on and off at slow speeds and remain on steady at high speeds.

Correct operation of the ROS can be checked at any time by aiming it at an original design fluorescent light and observing a 120 Hz or 100 Hz (two times your mains frequency) square wave on the signal output. If the sensor is being used with a tachometer, the tachometer will read 7200 RPM or 6000 RPM. The Sensor will not pick up newer "energy efficient" design fluorescent lights.

### ACCESSORIES:

EC-25P 25 foot [7.6 m] Extension Cable T-5 Reflective Tape - 5 foot [1.5 m] roll ROS-NUT Set of two M16 Jam Nuts ROS-MNT 90° Slotted Mounting Bracket Waterproof Reflective Tape - 5 foot [1.5 m] roll Self Powered Sensor - Interface Module T-5WP SPS-IM 3-wire shielded Sensor Cable, bulk lengths PLUG 3.5 mm [1/8 inch] male stereo plug

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